

a) General			
<i>School</i>	ENGINEERING		
<i>Academic unit</i>	MECHANICAL ENGINEERING		
<i>Level of studies</i>	Undergraduate		
<i>Course code</i>	MM209Y01	<i>Semester</i>	9
<i>Course title</i>	Mechatronics		
<i>Independent teaching activities</i>	<i>Weekly teaching hours</i>	<i>ECTS</i>	
Lectures	4	7.0	
Laboratory exercises	1		
<i>Course type</i>	Knowledge deepening / consolidation		
<i>Course category</i>	Compulsory for Direction 2		
<i>Prerequisite courses</i>	-		
<i>Language of instruction and examinations</i>	Greek		
<i>Is the course offered to Erasmus students</i>	Yes (EN)		
<i>Course website (url)</i>	https://eclass.uniwa.gr/courses/MECH156/		
b) Learning outcomes and general competences			
b1. Learning outcomes			
Upon successful completion of this course, the student will be able to:			
<ul style="list-style-type: none"> - Recognize the parts of a Mechatronic system and identify the component sub-systems. - Interpret the structure of a mechatronic system in terms of blocks and signal flows. - Develop interfaces for common sensors and actuators. - Develop real-time software for mechatronics applications. - Implement simple control systems using mechatronics technologies and methods. 			
b2. General competences			
<ul style="list-style-type: none"> - Search for, analysis and synthesis of data and information with the use of the necessary technology - Adapting to new situations - Decision making - Working independently - Team work - Working in an international environment - Working in an interdisciplinary environment. 			
c) Syllabus			
Introduction to Mechatronics, basic mechatronic system layout, sensors, actuators, micro-controllers, programming for real-time, mechatronics applications.			
d) Teaching and learning methods - Evaluation			
<i>Delivery</i>	Live lectures		
<i>Use of information and communications technology</i>	<ul style="list-style-type: none"> - Commercial and free / open source software - Multimedia applications - MS Teams, eClass 		
<i>Teaching methods</i>	<i>Activity</i>	<i>Semester workload</i>	
	Lectures	39	
	Tutorials		
	Laboratory exercises	26	

	Computational exercises	
	Individual work	91
	Course total	156
Student performance evaluation	Written final examination and student project (coursework).	
e) Suggested bibliography		
<ol style="list-style-type: none"> 1. Nesculescu D. (2001). <i>Mechatronics</i>. Pearson. 2. Auslander D.M. & Kempf C.J. (2000). <i>Mechatronics: Mechanical Systems Interfacing</i>. Prentice Hall. 3. Stifler K. (1992). <i>Design with Microprocessors for Mechanical Engineers</i>. McGraw Hill 		